

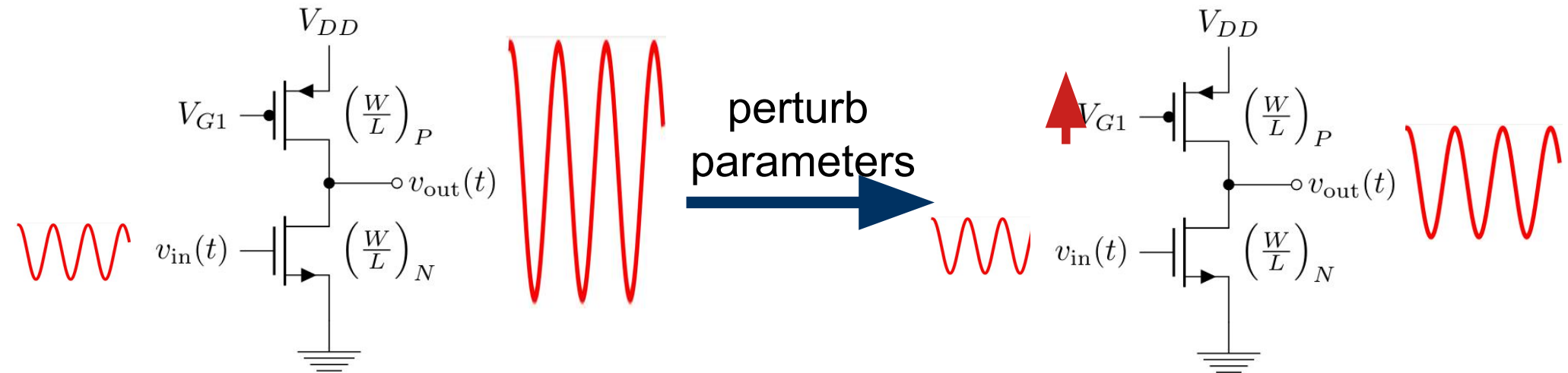
# **TADsens: Transient Adjoint DAE Sensitivities**

Naomi Sagan, Jaijeet Roychowdhury

EECS Department  
University of California, Berkeley

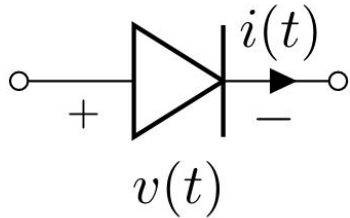
# Importance of Transient Sensitivities

- **Context:** transient circuit simulation
- **Circuit parameters:** MOSFET dimensions, resistors, capacitors, supply voltages, *etc.*
- **Sensitivities = change in circuit output for a given change in parameter values**

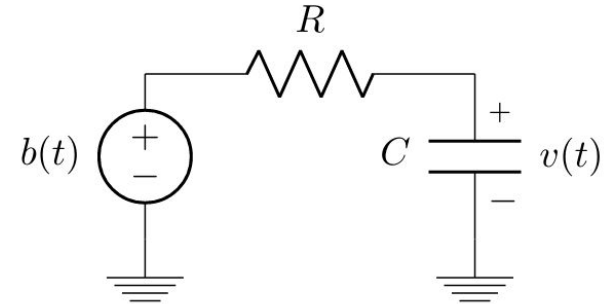


# Circuit Representations

Device + network equations in terms of voltages, currents

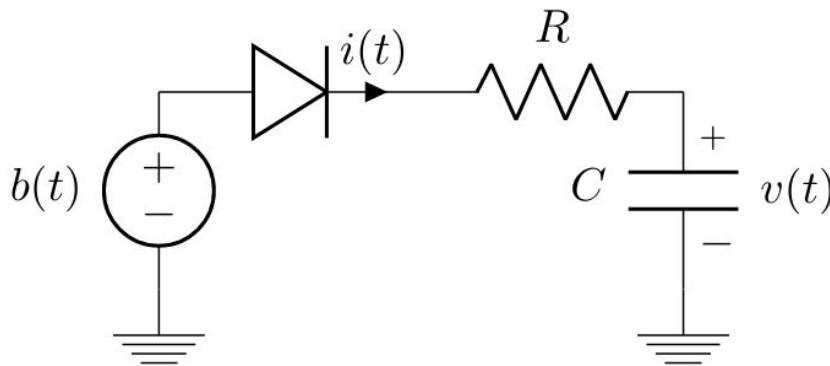


$$i(t) = I_s (e^{-v(t)/V_T} - 1)$$



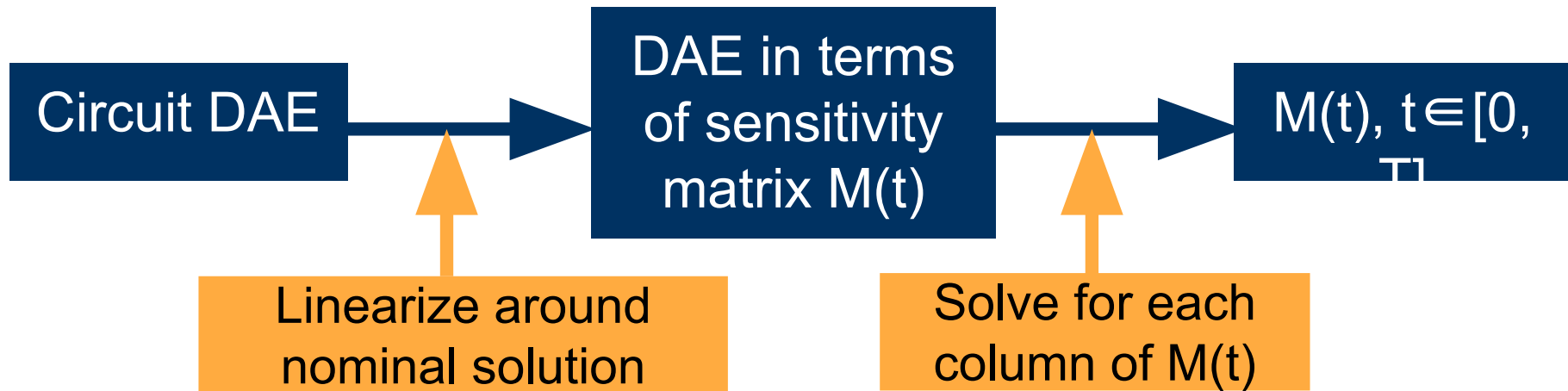
$$\frac{dv}{dt} = -\frac{v(t) - u(t)}{RC}$$

DAE: system of differential and algebraic equations

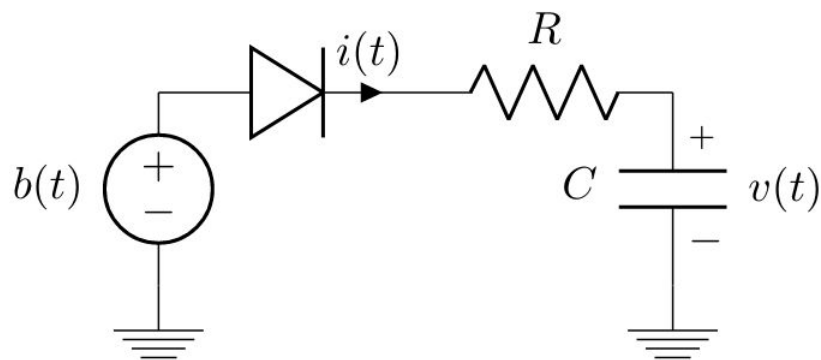


$$\begin{cases} \text{algebraic} \\ i(t) = I_s \left( \exp \left( \frac{u(t) - i(t)R - v(t)}{V_T} \right) - 1 \right) \\ \text{differential} \\ \frac{dv}{dt} = \frac{i(t)}{C} \end{cases}$$

# Direct Sensitivity Computation

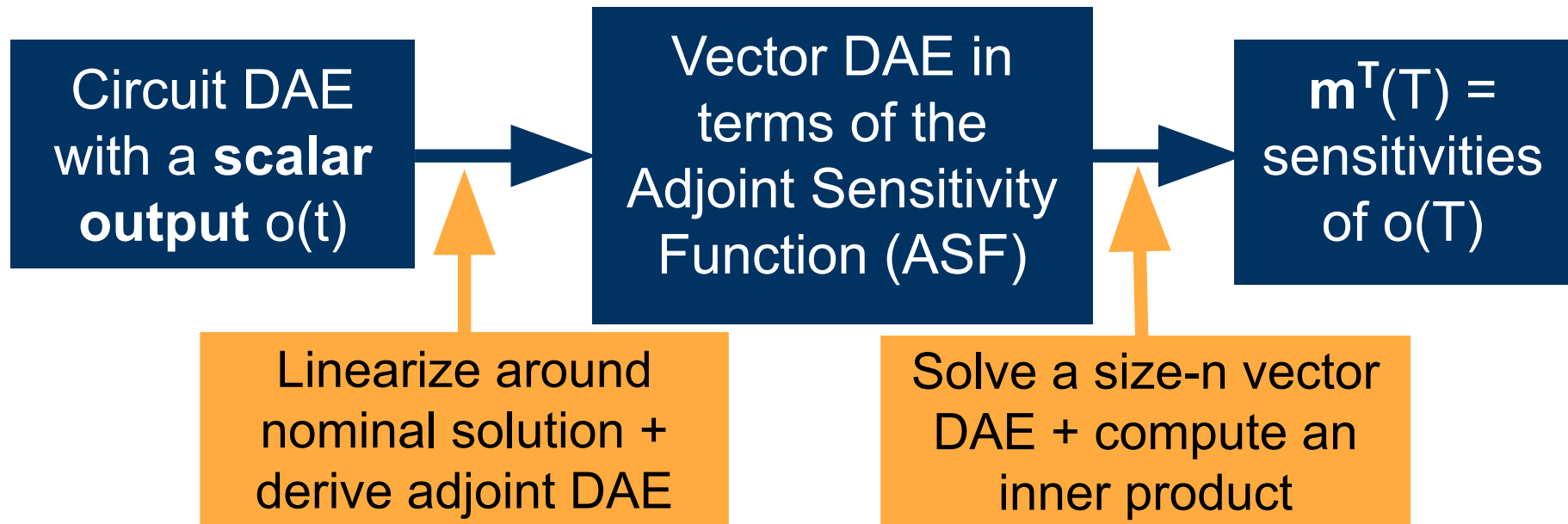


- $M(t)$  is a dense sensitivity matrix of size  $n \times n_p$ ,  $M(t) = \frac{\partial \vec{x}}{\partial \vec{p}}$
- Solving the sensitivity DAE has complexity  $O(nn_p T)$
- This is infeasible for circuits with large numbers of parameters

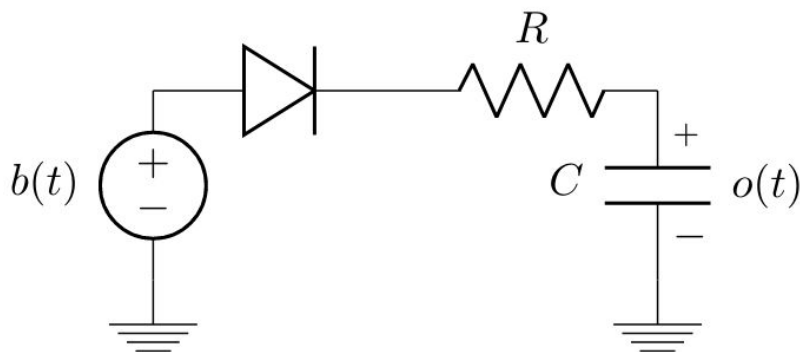


$$\mathbf{M}(t) = \begin{bmatrix} \text{Sens. of } v(t) \text{ to } R & \text{Sens. of } v(t) \text{ to } C \\ \text{Sens. of } i(t) \text{ to } R & \text{Sens. of } i(t) \text{ to } C \end{bmatrix}$$

# Adjoint Sensitivity Computation



- We typically care about only a few circuit outputs
- Complexity  $O((n+n_o)T)$ : much more efficient than direct



$$\vec{m}^T(T) = [\text{Sens. of } o(T) \text{ to } R \quad \text{Sens. to } C]$$

# Sensitivity Computation – History

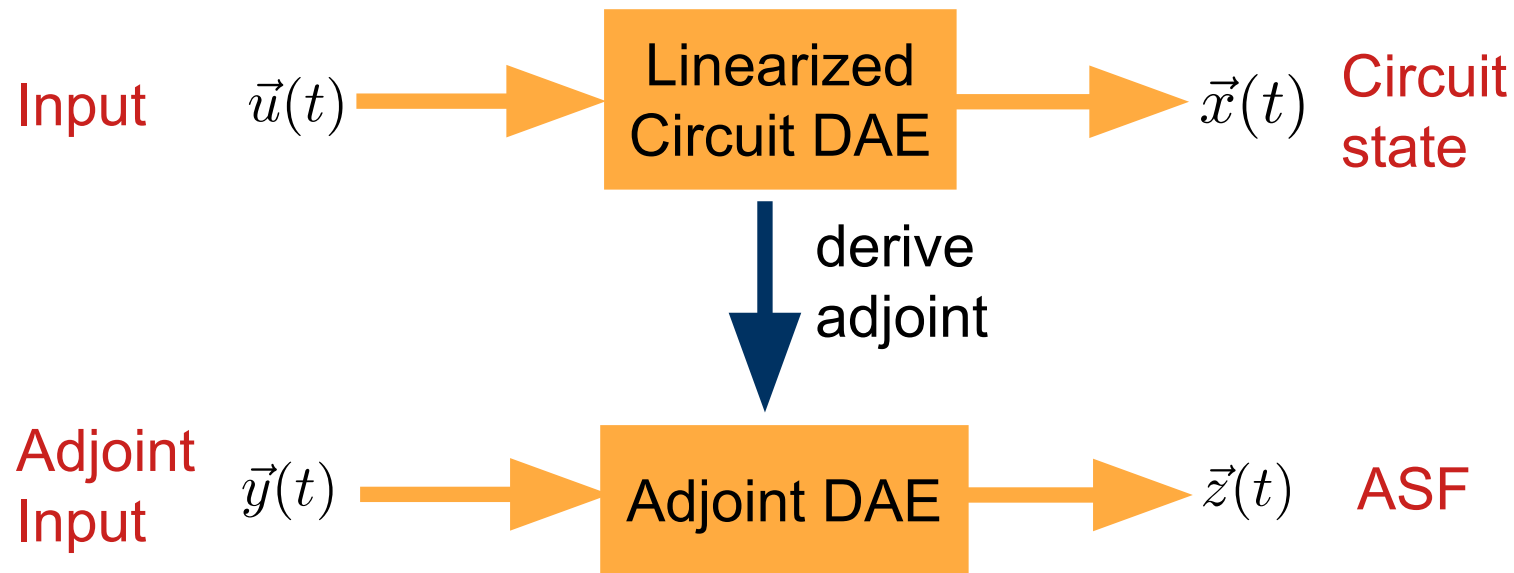
- Direct computation only:
  - D. Hocevar, P. Yang, T. Trick, and B. Epler, 1985
- Specialized techniques:
  - S. Director and R. Rohrer, 1969
  - P. Feldmann, T. V. Nguyen, S. W. Director, and R. A. Rohrer, 1991

Only for a few circuit elements  
simulator-specific
- A priori discretization:
  - F. Liu and P. Feldmann, 2014.
  - K.V. Aadithya, E. Keiter and T. Mei, 2017.

Constraints on form of DAE
- ODEs or special DAE forms:
  - Y. Cao, S. Li, L. Petzold, and R. Serban, 2003.
  - A. Meir and J. Roychowdhury, 2012.

ODE only

# Adjoint Operators and Inner Products

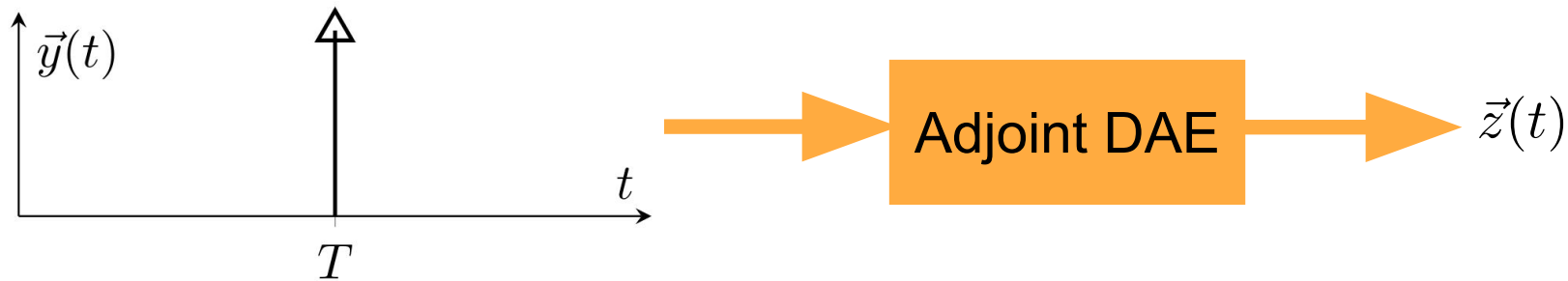


Inner product relationship:  $\langle \vec{x}(t), \vec{y}(t) \rangle = \langle \vec{u}(t), \vec{z}(t) \rangle$

Note: the inner product of two vector functions is defined as

$$\langle \vec{x}(t), \vec{y}(t) \rangle = \int \vec{y}^T(t) \vec{x}(t) dt$$

# Dirac $\delta$ Input into the Adjoint DAE



- This  $\delta$ -function input allows us to isolate the sensitivities at time  $T$  via the adjoint inner product relationship.
- If we know the ASF, we can compute the sensitivities of  $o(T)$

$$\langle \vec{x}(t), \vec{c}\delta(t - T) \rangle = \text{[Graph of } \vec{x}(t) \text{ with a vertical arrow at } T \text{ labeled } (\vec{c}) \text{]} = \vec{c}^T \vec{x}(T)$$

The equation shows the inner product of a state vector  $\vec{x}(t)$  with a Dirac delta function  $\vec{c}\delta(t - T)$ . The graph shows a pink oscillating curve  $\vec{x}(t)$  over time  $t$ . A vertical blue arrow points upwards from the horizontal axis at time  $T$ , labeled  $(\vec{c})$ . The result of the inner product is the dot product of  $\vec{c}$  and the state vector at time  $T$ ,  $\vec{c}^T \vec{x}(T)$ .

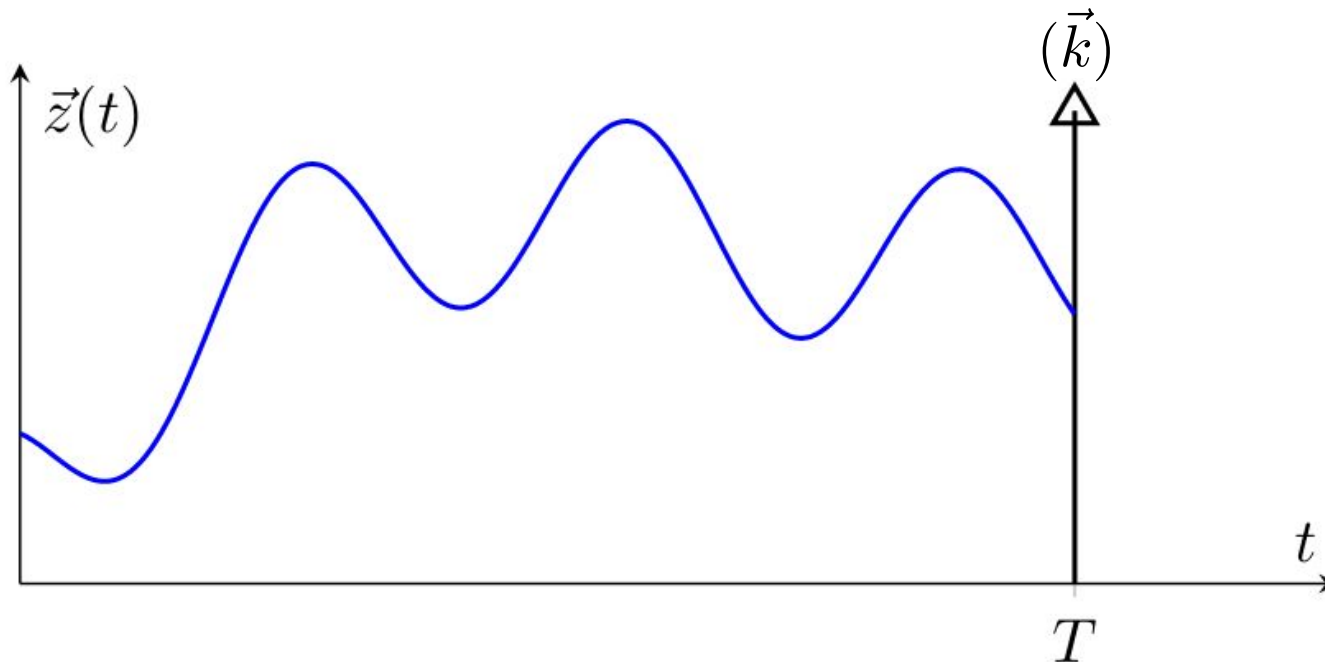


# Consequences of $\delta$ -Function Input

- Problem:  $\infty$ -valued, cannot be accurately represented numerically
- Solution: assume the ASF is of the form

$$\vec{z}(t) = \vec{z}_1(t) + \vec{k}\delta(t - T)$$

- and analytically derive  $\vec{z}_1(t)$  and  $\vec{k}$



# Deriving the ASF

Infinitesimal integration of adjoint DAE at time  $T$



Derive analytical expressions for  $\mathbf{k}$  and  $\mathbf{z1}(T-)$



Solve the adjoint DAE backwards from  $T-$  to  $0$  for  $\mathbf{z1}(t)$

All components in this range are finite-valued



Compute sensitivities using adjoint inner-product relationship

# The Adjoint DAE

Circuit  
DAE

$$\frac{d}{dt} \underline{\vec{q}(\vec{x}(t))} + \underline{\vec{f}(\vec{x}(t))} + \vec{b}(t) = \vec{0}$$

- Solve DAE with nominal parameters for solution  $\vec{x}_{\text{nom}}(t)$
- Linearize around nominal parameters and solution

Linearized  
DAE

$$\frac{d}{dt} \mathbf{C}(t) \underline{\Delta \vec{x}(t)} + \mathbf{G}(t) \underline{\Delta \vec{x}(t)} = \underline{-\mathbf{S}(t) \Delta \vec{p}}$$

where

$$\mathbf{C}(t) = \frac{\partial \vec{q}}{\partial \vec{x}}, \mathbf{G}(t) = \frac{\partial \vec{f}}{\partial \vec{x}}, \mathbf{S}(t) = \frac{d}{dt} \frac{\partial \vec{q}}{\partial \vec{p}} + \frac{\partial \vec{f}}{\partial \vec{p}}$$

Adjoint  
DAE

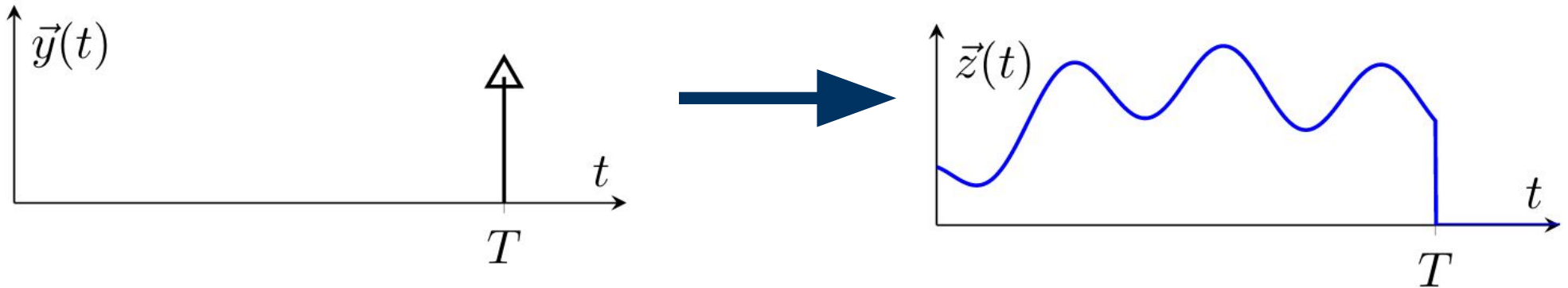
$$-\mathbf{C}^T(t) \frac{d}{dt} \vec{z}(t) + \mathbf{G}^T(t) \vec{z}(t) = \vec{y}(t)$$

# ASF for ODEs and Algebraic Equations

## ODEs

$$\frac{d}{dt}\vec{x}(t) + \vec{f}(\vec{x}(t)) = \vec{b}(t)$$

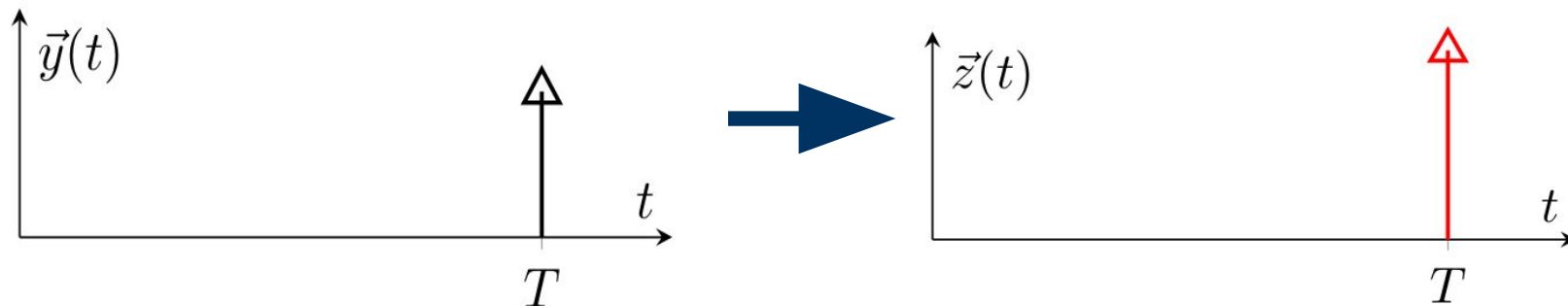
- Adjoint DAE is a linear time-varying ODE:  $\frac{d}{dt}\vec{z}(t) - \mathbf{G}^T(t)\vec{z}(t) = \vec{y}(t)$



## Algebraic Equations

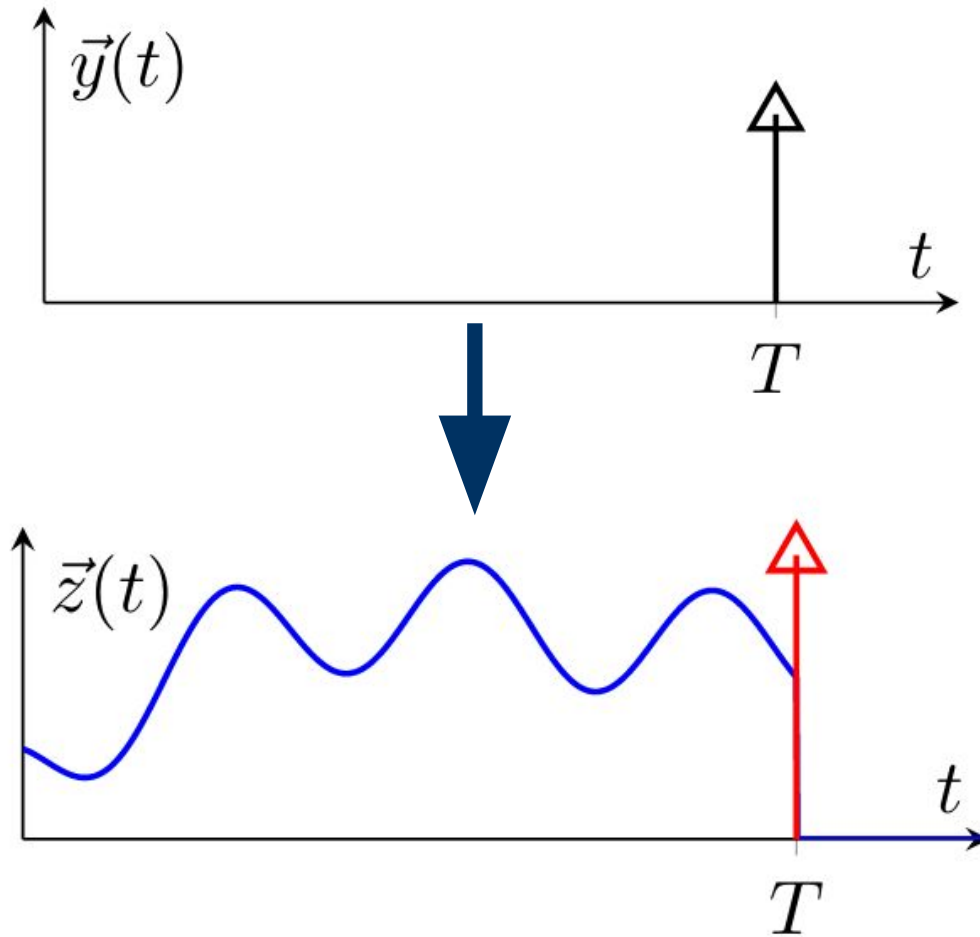
$$\vec{f}(\vec{x}(t)) = \vec{b}(t)$$

- Adjoint DAE is a system of algebraic equations:  $\mathbf{G}^T(t)\vec{z}(t) = \vec{y}(t)$



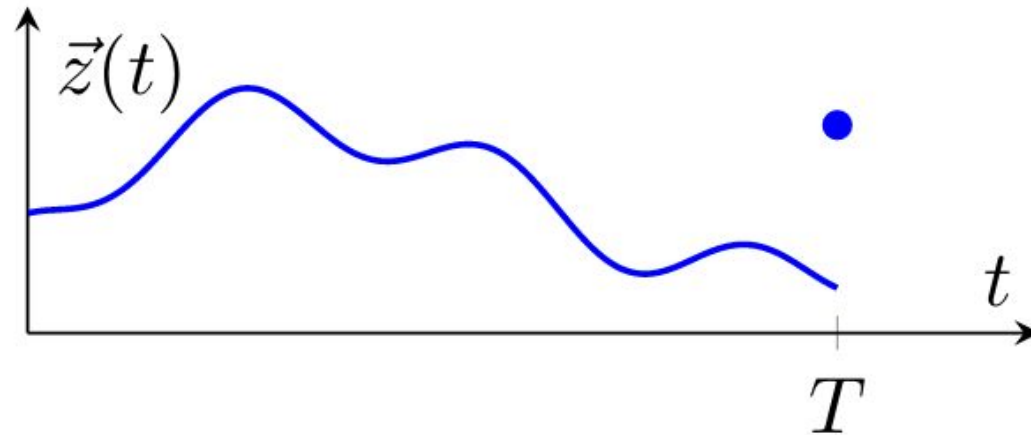
# ASF for DAEs

- An impulsive input into the adjoint DAE results in an impulsive output superposed onto a finite waveform



# Discontinuity in Computing the ASF

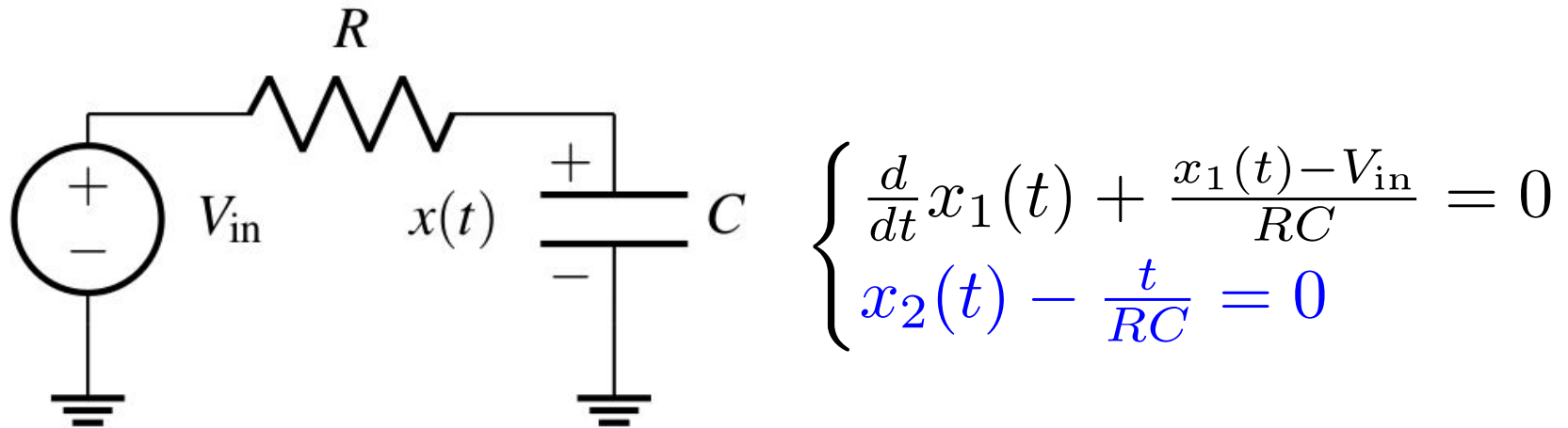
$\mathbf{C}(T)$  rank-deficient  $\longrightarrow$  Final condition  $\mathbf{z}_1(T^-)$  may be inconsistent



- Issues in numerically integrating  $\mathbf{z}_1(t)$  to get final sensitivities
- **Solution:** take a small first transient timestep and discard  $\mathbf{z}_1(T)$

# Results: Simple Size-2 DAE

- **Goal:** Illustrate using a hand-calculable example
- **System:** size-two DAE:
- RC ODE with separate algebraic equation added on

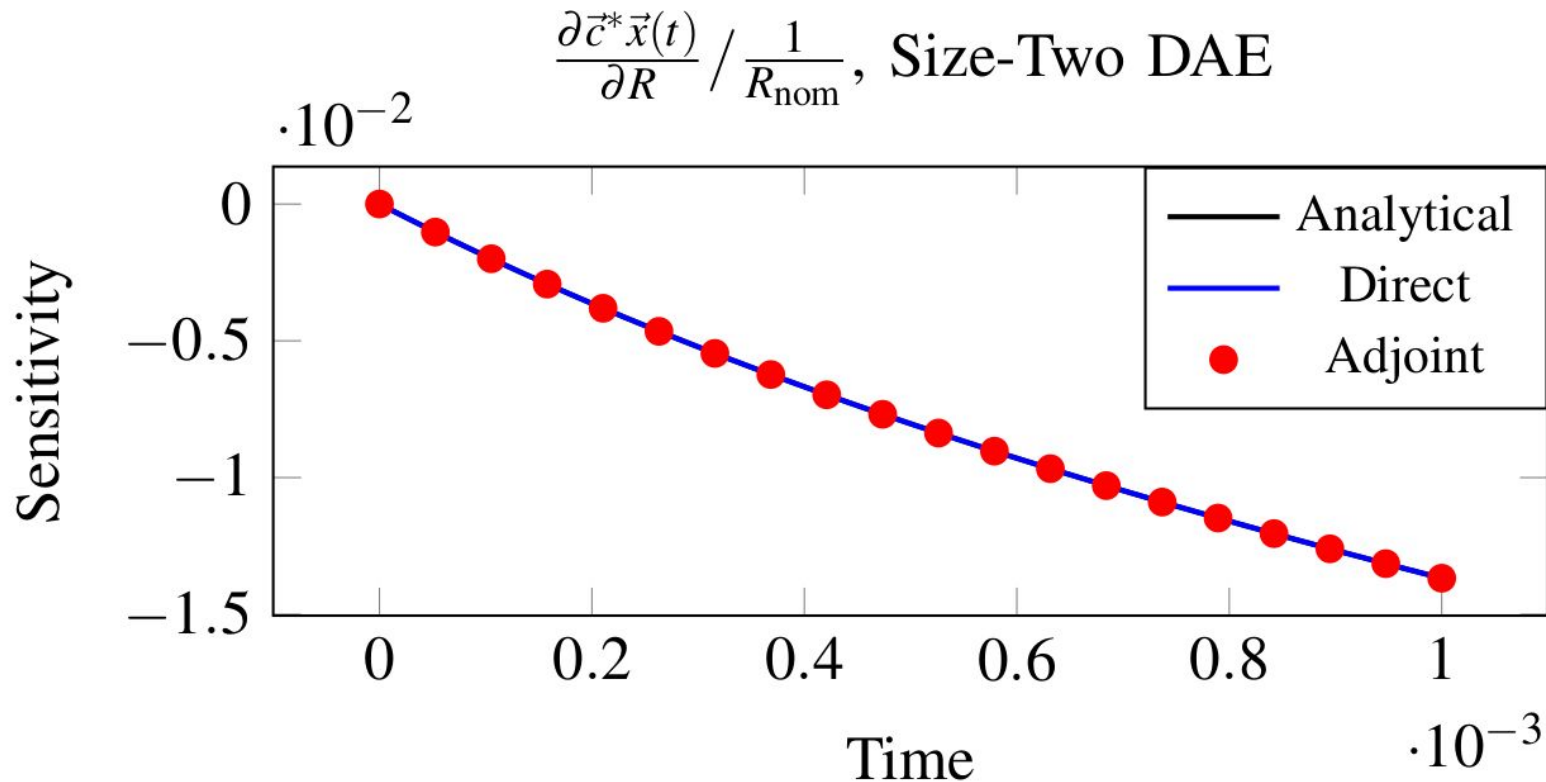


- **Analytical sensitivities:**

$$\frac{\partial \vec{x}}{\partial \vec{p}} = \begin{bmatrix} \frac{t}{R^2 C} (x_1(0) - V_{in}) e^{-\frac{t}{RC}} & \frac{t}{C^2 R} (x_0 - V_{in}) e^{-\frac{t}{RC}} \\ -\frac{t}{R^2 C} & -\frac{t}{RC^2} \end{bmatrix}.$$

# Results: Simple Size-2 DAE

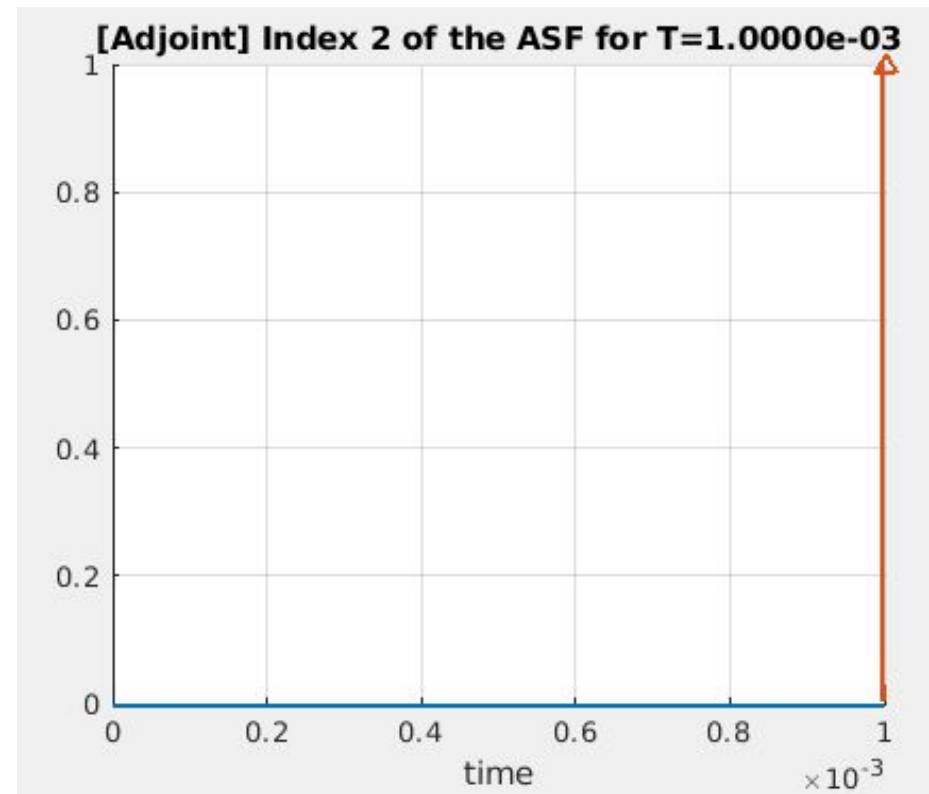
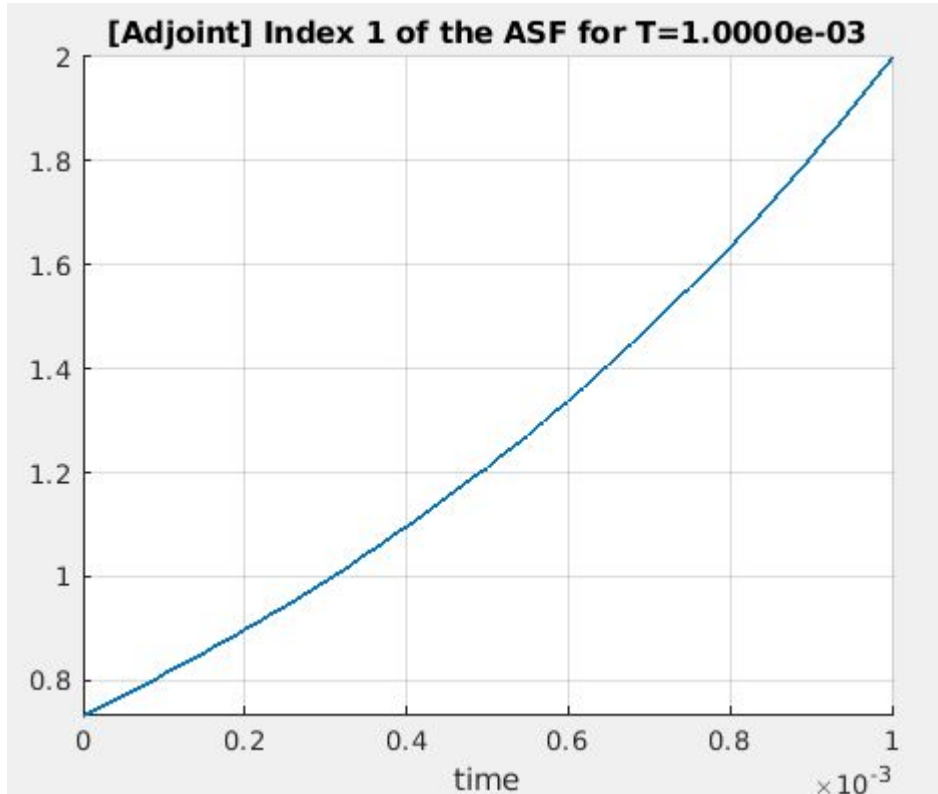
- **Setup:** output =  $2\mathbf{x}_1(t) + \mathbf{x}_2(t)$ ,  $R = 1 \text{ k}\Omega$ ,  $C = 1 \text{ }\mu\text{F}$ ,  $T = 1 \text{ ms}$
- **Plot:** Analytical, direct, and adjoint sensitivities to  $R$  over time (change in output per percent change in  $R$ )





# Results: Simple Size-2 DAE

ASF for  $T = 1 \text{ ms}$ ,  $o(t) = 2x_1(t) + x_2(t)$



## Sensitivities at T:

- To R:  $-1.3679e-03 \text{ V/Ohm}$
- To C:  $-1.3679e+06 \text{ V/F}$

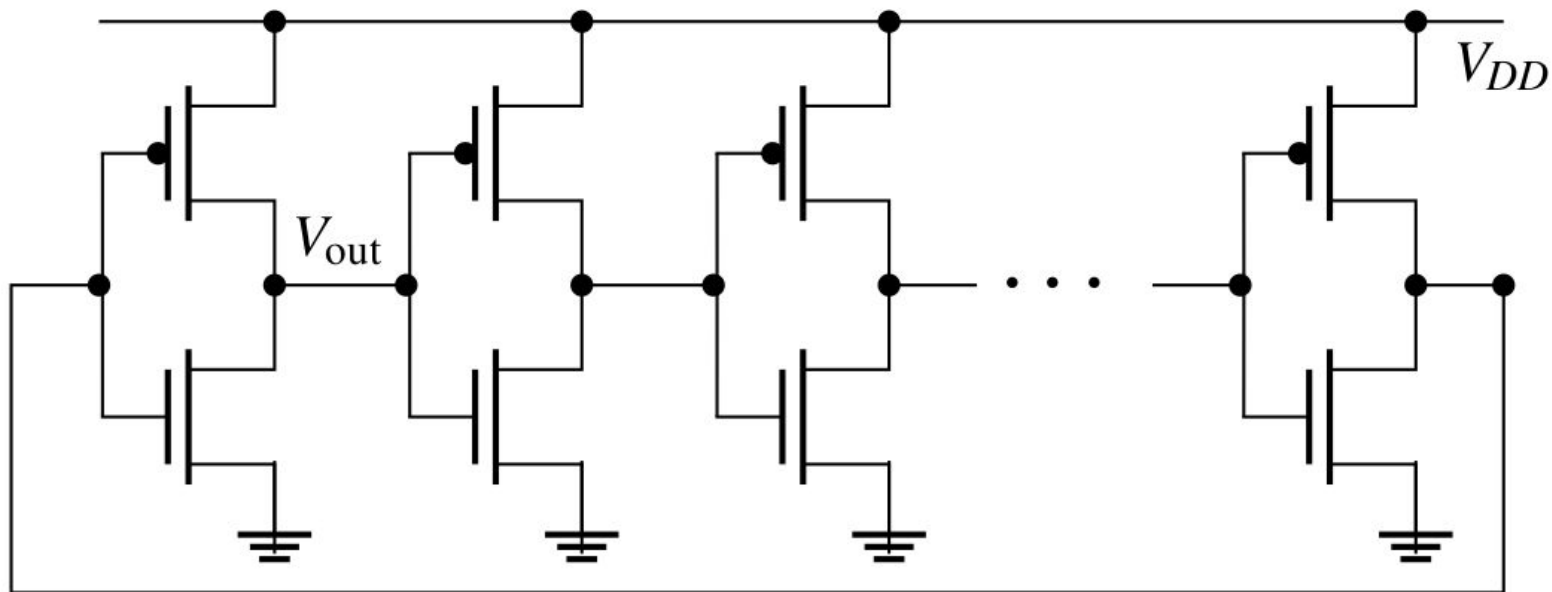


## Normalized by pNom value:

- To R:  $-1.3679e-02 \text{ V/\%}$
- To C:  $-1.3679e-02 \text{ V/\%}$

# Results: 51-Stage MOS Ring Osc.

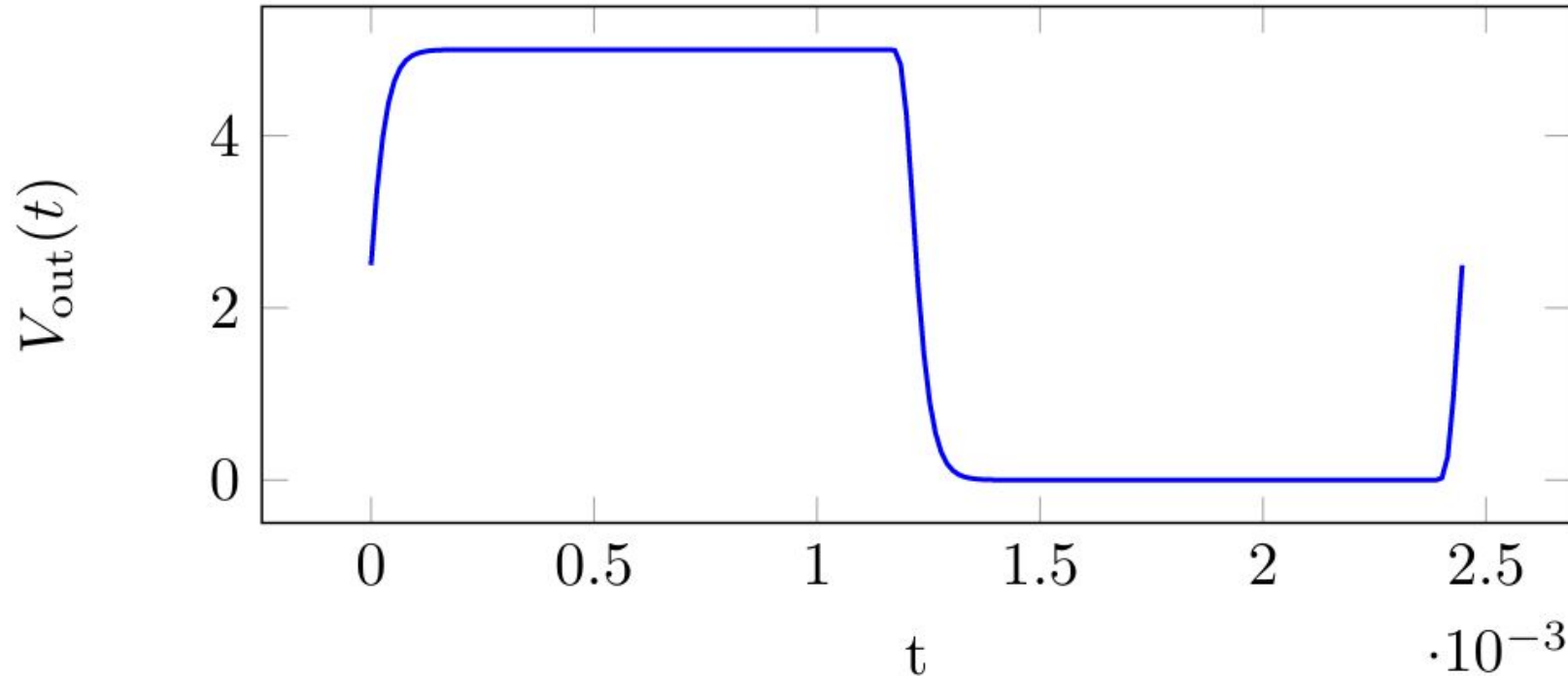
- **Goal:** Efficiency on a larger, more interesting circuit
- **System:** 51-stage MOS ring oscillator



- **155 unknowns, 664 parameters**

# Results: 51-Stage MOS Ring Osc.

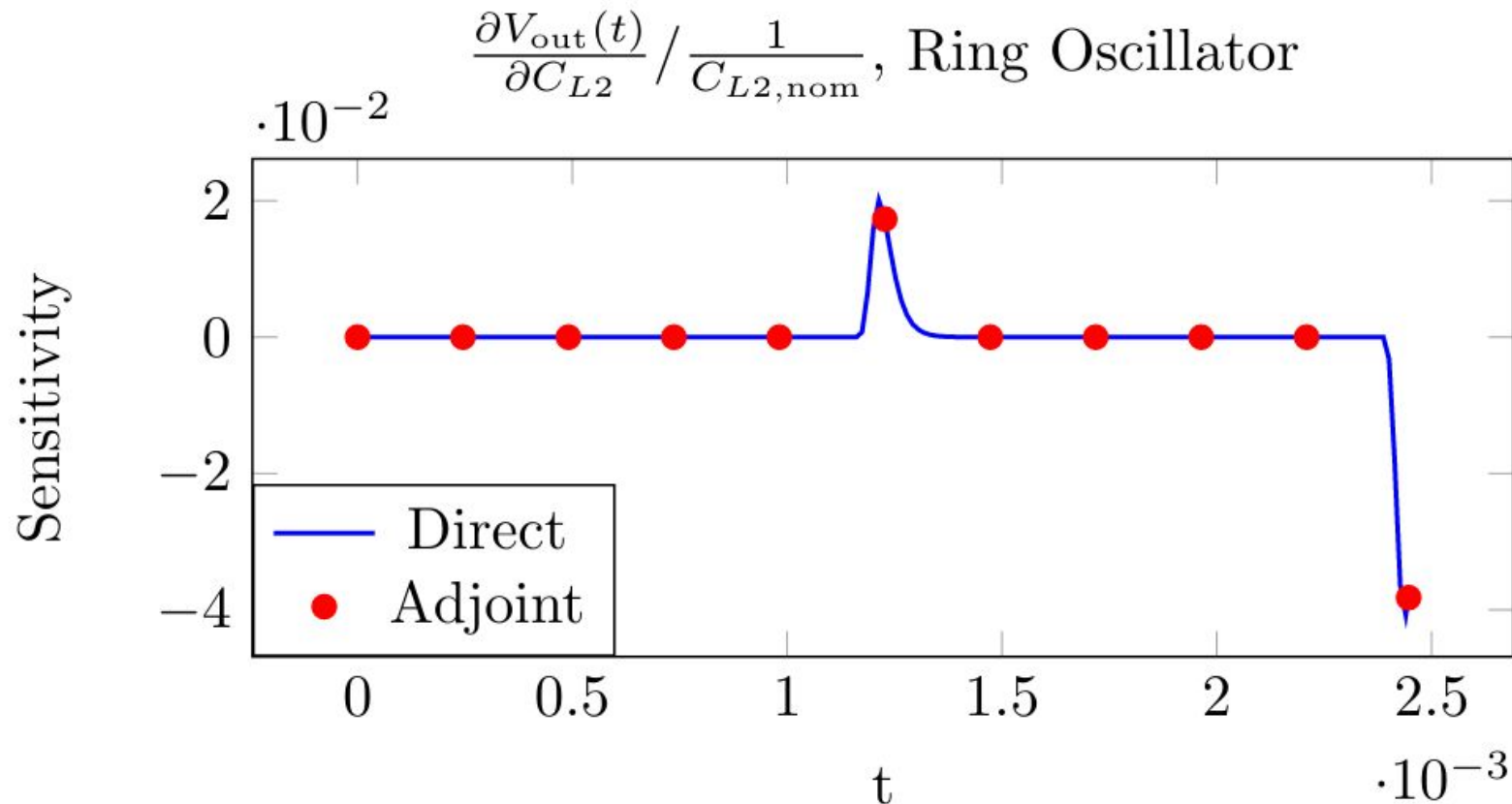
## Nominal Output Waveform



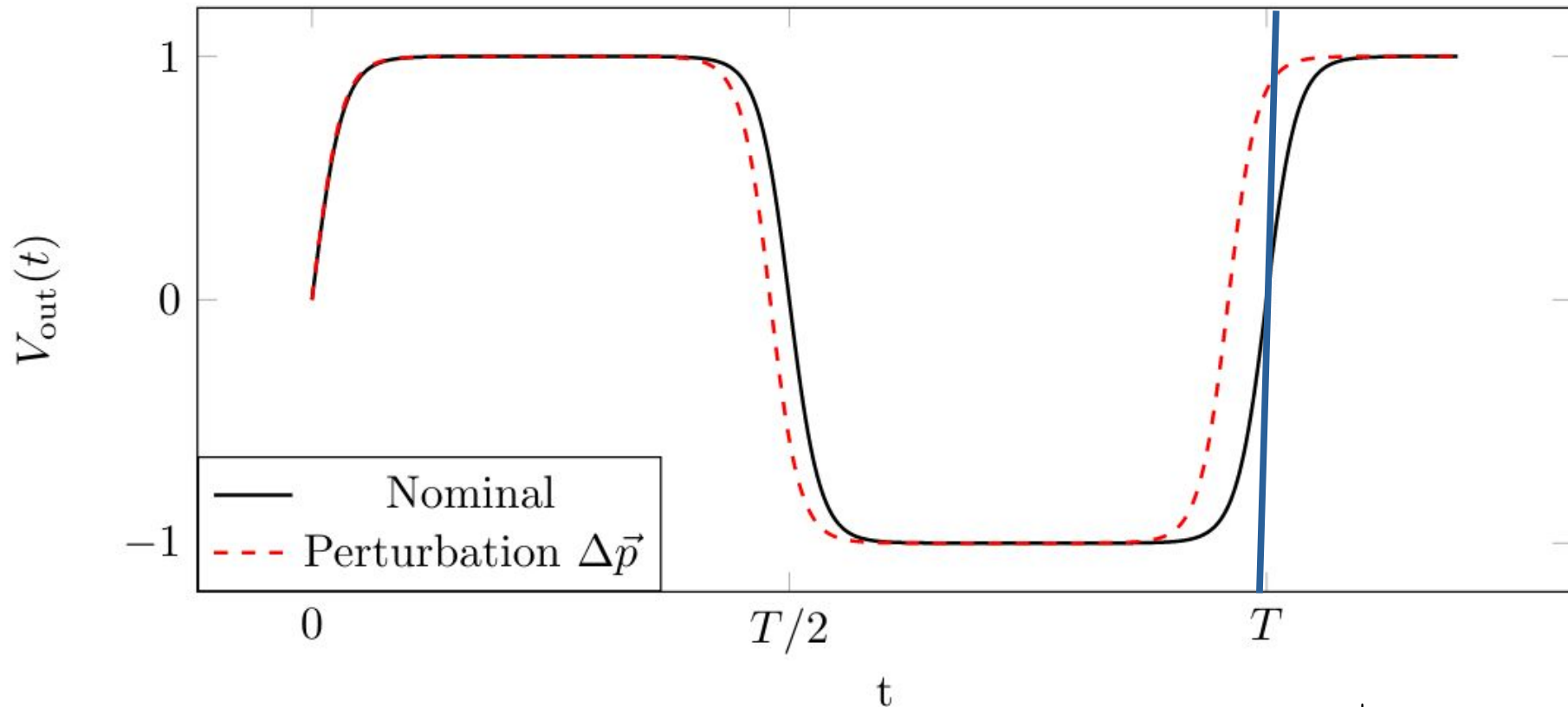
- **Setup:** 3000 timepoints over one oscillator period ( $T = 2.447$  ms)
- **Most important parameters:** load capacitors at output of each inverter
- **Runtime: direct = 7392 s, adjoint = 24.6 s**

# Results: 51-Stage MOS Ring Osc.

- **Plot:** sensitivities of output to load cap at output
- Normalized by nominal parameter value



# Results: Sensitivity of Ring Oscillator Period



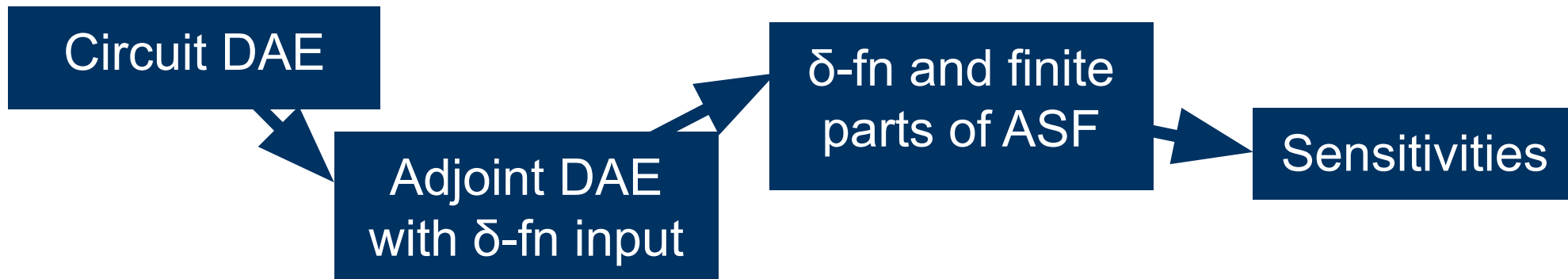
- **Want:**  $\Delta T$ , given  $\Delta V/\Delta \mathbf{p}$  and  $dV/dt$ : 
$$\frac{\partial T_{\text{osc}}}{\partial \vec{p}} = \frac{\partial v(t)/\partial \vec{p}|_{T_{\text{nom}}}}{dv(t)/dt|_{T_{\text{nom}}}}$$
- **Result:** a 1% change in the output load capacitance will cause a 0.0209% change in the oscillator period

# Summary

## Problem

- Devise an efficient and numerically well-defined method for computing sensitivities of circuit outputs via adjoints

## Process of Deriving Sensitivities



## Results

- **Accurate + faster than direct**